

# Bearing Equivalent Load

## Combining Axial and Radial Forces Applied to a Bearing

### Background

Bearing life calculation is based on a single direction load. Calculating life for a bearing with both radial and axial forces applied requires combining them into a single equivalent load. These calculations seem complex reading manufacturers' catalogs. Each manufacturer presents their equations in differently. An individual manufacturer will present equations for each type of bearing they make differently. In reality the equivalent load equation (Equation 1) is the same. It can be generalized by always showing the factors ( $X_n$ ,  $Y_n$ ) weighting the radial ( $F_r$ ) and axial ( $F_a$ ) forces.

**Equation 1**

$$P = X_n \times F_r + Y_n \times F_a$$

Depending on the manufacturer, bearing type and loading condition the weighting factors can be constants, or variable equations (Table 1). In many cases the constants can be one or zero. In these cases manufacturers show the simplified equation (example Equation 2).

**Equation 2**

$$X_n = 1 \text{ \& } Y_n = 0 \xrightarrow{\text{yields}} P = F_r$$

Understanding that the multitude of equations presented by manufacturers is actually one equation makes programming the calculation much simpler (see Excel Functions in Visual Basic).

### Nomenclature

$e$  = Load Ratio Threshold for Equation Use

$P$  = Equivalent load used in life calculation of combined radial and axial loads applied to the bearing

$F_a$  = Axial Force

$F_r$  = Radial Force

$X_n$  = Factor for weighting radial force.

$Y_n$  = Factor for weighting axial force. Timken calls this  $K$  in their catalog

### Dynamic Calculation

Equivalent load ( $P$ ) is used to combine axial load ( $F_a$ ) and radial load ( $F_r$ ) to use in the bearing life equation.

If

**Equation 3**

$$\frac{F_a}{F_r} \leq e$$

Then

**Equation 4**

$$P = X_1 \times F_r + Y_1 \times F_a$$

Else →

If

**Equation 5**

$$\frac{F_a}{F_r} > e$$

Then

**Equation 6**

$$P = X_2 \times F_r + Y_2 \times F_a$$

$e$  determines which equation to use to find  $P$

<b>Table 1</b>	$e$	$Y_1$	$X_1$	$Y_2$	$X_2$
Deep Row Ball	Equation 7	0	1	Equation 8	Table 2
Angular Contact Ball Single	1.14	0	1	0.57	0.35
Angular Contact Ball Tandem Pair	1.14	0	1	0.57	0.35
Angular Contact Ball Pair X or O	1.14	0.55	1	0.93	0.57
Cylindrical Roller**	Catalog*	0	1	Catalog*	0.92
Taper Roller Timken	Equation 9	0	1	Catalog*	0.40
Taper Roller SKF	Catalog*	0	1	Catalog*	0.40
Spherical Roller	Catalog*	Catalog*	1	Catalog*	0.67

\*Catalog= See Manufacturer's catalog to find factor for the exact bearing being used. Note that  $Y_2$  will probably simply be called  $Y$  cases where  $Y_1=0$  or any other fixed value

\*\*Cylindrical Roller Bearings with axial should to take thrust load should only be used for light loads. See the manufacturer's catalog for details on limitations due to heat generation.

<b>Equation 7</b>	$e = 10^{[e_{B1} \times \log(\frac{F_a}{C_0}) - e_{B2}]}$	1. For Deep Row Ball Bearings 2. Derived from Tables in FAG & SKF Catalogs 3. See Table 2 for factors to use by fit class
<b>Equation 8</b>	$Y_2 = 10^{[Y_{B1} \times \log(\frac{F_a}{C_0}) + Y_{B2}]}$	

<b>Table 2</b>	Deep Row Ball Bearing Factors by Class of Fit Derived from Tables in FAG & SKF Catalogs					
	Fit	$e_{B1}$	$e_{B2}$	$Y_{B1}$	$Y_{B2}$	$X_2$
	Normal	0.235	0.290	0.235	0.070	0.560
	C3	0.190	0.220	0.190	0.057	0.460
	C4	0.117	0.220	0.117	0.035	0.440

<b>Equation 9</b>	$e = \frac{R}{Y_2} \xrightarrow{\text{yields}} e = \frac{0.40}{Y_2}$	$e$ for dynamic calculations on Timken Taper Roller Bearings
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## Static Calculation

Equivalent load ( $P_0$ ) is used to combine axial load ( $F_a$ ) and radial load ( $F_r$ ) to compare to the static load rating ( $C_0$ ). If the static load rating is exceed a single application will cause failure. Therefore the life calculation does not apply. These are the same equations as for dynamic except  $0$  notation is used denoting to use static factors to get static results.

If <b>Equation 10</b> $\frac{F_a}{F_r} \leq e_0$ Then <b>Equation 11</b> $P_0 = X_{10} \times F_r + Y_{10} \times F_a$	Else →	If <b>Equation 12</b> $\frac{F_a}{F_r} > e_0$ Then <b>Equation 13</b> $P_0 = X_{20} \times F_r + Y_{20} \times F_a$
$e_0$ determines which equation to use to find $P_0$		

<b>Table 3</b>	$e_0$	$Y_{10}$	$X_{10}$	$Y_{20}$	$X_{20}$
Deep Row Ball	Equation 14	0	1	0.50	0.60
Angular Contact Ball Single	Equation 14	0	1	0.26	0.50
Angular Contact Ball Tandem Pair	Equation 14	0	1	0.26	0.50
Angular Contact Ball Pair X or O	Equation 14	0	1	0.52	1
Cylindrical Roller	0	0	1	0	1
Taper Roller Timken	Equation 15	Equation 16	1.6	Equation 17	0.50
Taper Roller SKF	Equation 14	0	1	Catalog*	0.50
Spherical Roller	0	Catalog*	1	Catalog*	1

\*Catalog= See Manufacturer's catalog to find factor for the exact bearing being used

<b>Equation 14</b>	$e_0 = \frac{1 - X_{20}}{Y_{20}}$	$e$ for static calculations
<b>Equation 15</b>	$e_0 = 0.6 \times e \xrightarrow{\text{yields}} e_0 = \frac{0.24}{Y_2}$	$e$ for static calculations on Timken Taper Roller Bearings
<b>Equation 16</b>	$Y_{10} = 1.269 \times Y_2$	$Y_1$ for static calculations on Timken Taper Roller Bearings
<b>Equation 17</b>	$Y_{20} = 0.564 \times Y_2$	$Y_2$ for static calculations on Timken Taper Roller Bearings

## Excel Functions in Visual Basic

```
Public Function EqLoad(X1, Y1, X2, Y2, e, Fr, Fa)
    ' Generalized Equivalent load Equation
    If Fr = 0 Then Fr = 0.0000001 'Stops error if Fr or Fa are zero
    If Fa = 0 Then Fa = 0.0000001
    Fa = Abs(Fa)
    If Fa / Fr > e Then
        EqLoad = X2 * Fr + Y2 * Fa
    Else
        EqLoad = X1 * Fr + Y1 * Fa
    End If
End Function
```

```
Public Function DpRwBall_Y2(Y_1, Y_2, C0, Fa)
    ' Deep Row Ball Brg Equations to find Y2
    DpRwBall_Y2 = 10 ^ (-(Y_1 * Log10(Fa / C0) + Y_2))
End Function
```

```
Public Function DpRwBall_e(e_1, e_2, C0, Fa)
    ' Deep Row Ball Brg Equation to find e
    DpRwBall_e = 10 ^ (e_1 * Log10(Fa / C0) - e_2)
End Function
```

```
Public Function Log10(x)
    ' Needed sub function for Deep Row e Calculation
    Log10 = Log(x) / Log(10)
End Function
```

About the author:

**James K. Simonelli** is a Licensed Professional Engineer with 30 years experience designing and troubleshooting machine automation, heavy duty equipment and industrial products. He has a broad background with department head roles in engineering, quality and business development in companies varying from startups, turnarounds to Fortune 100 corporations. Mr. Simonelli has served on committees developing industrial standards for the American Gear Manufacturers Association and the Hydraulics Institute.

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